

# Drones and Public Safety

Integrating Drones into the incident means more than just having someone out there flying a Drone.

by

**Peter Hallenbeck**



# Today: Drones in the Air

- A drone is flown at an incident.
- All information is exchanged verbally over the radio.
- There might be a “Live Event” video stream on YouTube.

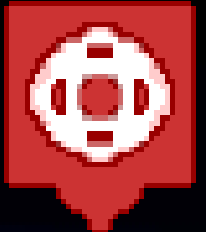

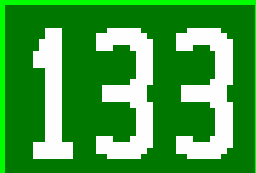






# Soon: Actual integration into the Fireground

- Data systems are being introduced into incident management.
- Map based displays for “Situational Awareness” are evolving.
- A central computer Server has lots of real time information about the incident.
- Responders have displays and user interfaces tailored to their role. They see the information they need to see for the job they need to do.

# The Example Scenario

- Rural Search and Rescue.
- Area covered: up to 100 Acres.
- Responders are looking for “something”.
- Could be a missing person, fugitive, hiker, responder.

# Incident Information Data

- Location given at Page-Out. 
- Drone Operations/Take-Off Location. 
- Responder Locations      
- Map Annotations: Drone Obstructions, Map Icons, “Targets” dropped by the drone pilot.
- Responder Health Information. 

# Responder Roles

- Incident Command - Overview of the entire incident.
- “Boots on the Ground” - The responders actually performing the search.
- Drone Operations - A Drone Operations Officer and a Drone Pilot.

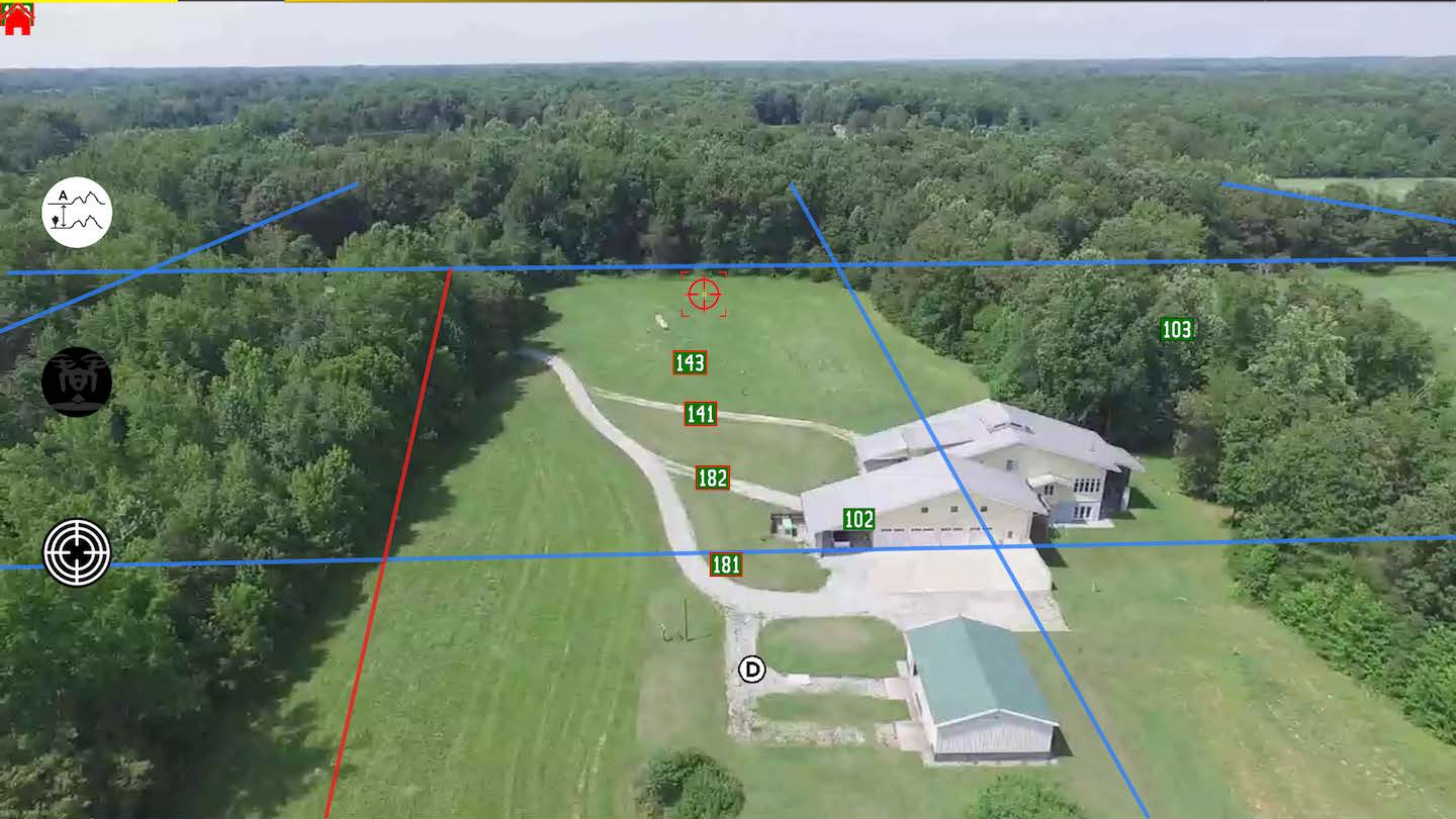
# Responder **Hardware** and **Software**

## **Software**

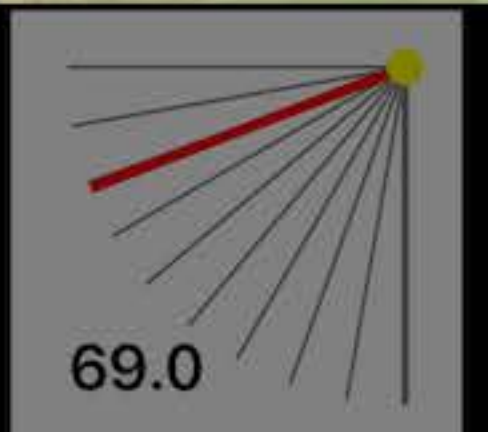
- Connects to the Server every few seconds.
- Retrieves incident information.
- Displays information relevant to the Responders Role.

## **Hardware**

- Smart Phones - Small size, small screens. (Boots on the Ground)
- Tablets - “iPad” - Medium size, medium screens. (Drone Pilot)
- Desktops/laptops - Big size, big or multiple screens. (Incident Command)



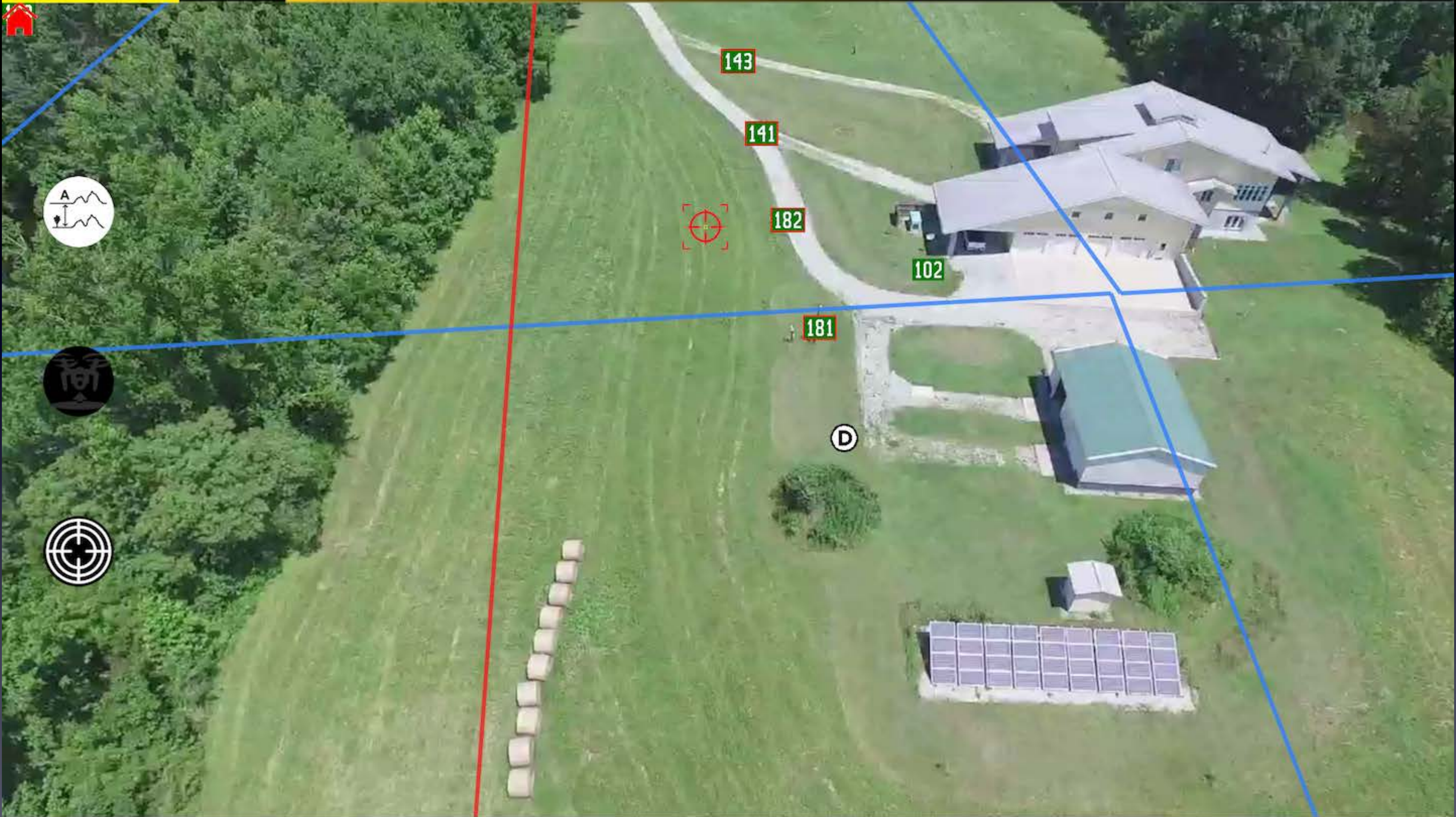
|  |                |                  |                 |                     |                      |
|--|----------------|------------------|-----------------|---------------------|----------------------|
|  | Wind<br>2 MPH  | Gusting<br>6 MPH | Temp °<br>92 F  | Vertical<br>0.0 MPH | DIST.<br>213 ft      |
|  | Speed<br>0 MPH | AGL<br>148 ft    | GPS-Ac<br>16 ft | Horizontal<br>0 MPH | Flight Time<br>03:30 |



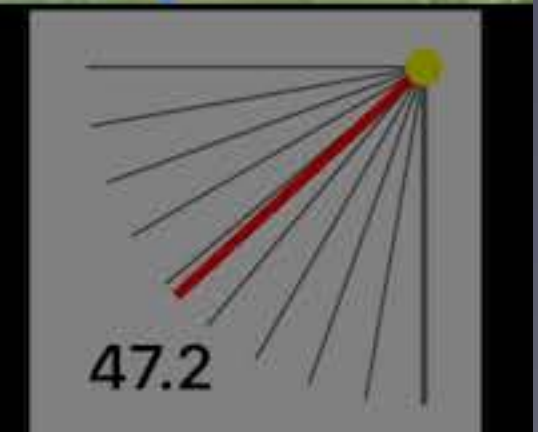
**Drone Pilot**

The Drone Pilot display shows the video, drone telemetry, weather, search grids, take-off point and responder locations.





|   |                |                  |                 |                     |                      |
|---|----------------|------------------|-----------------|---------------------|----------------------|
|  | Wind<br>3 MPH  | Gusting<br>5 MPH | Temp °<br>87 F  | Vertical<br>0.0 MPH | DIST.<br>194 ft      |
|  | Speed<br>0 MPH | AGL<br>194 ft    | GPS-Ac<br>16 ft | Horizontal<br>0 MPH | Flight Time<br>05:18 |



**Drone Pilot**  
 Same location  
 in the sky, but  
 at a *higher*  
 AGL altitude  
 but a *lower*  
 camera/gimba  
 l angle.

**Incident Command:** Sees where the drone is, where the drone has been, live video, weather, telemetry. (responder locations not shown on this view)

The image displays a Google Maps interface with a drone's location and flight path overlaid. The drone is marked with a 'D' in a circle and is positioned near a building labeled 'TEST'. A yellow line traces the drone's flight path across the landscape, which includes 'Brookhollow Rd', 'Masons Pond', and 'McGowan Creek'. A red line indicates a boundary or flight limit. On the left side of the map, there are zoom controls (+ and -) and a purple button labeled 'Video Off'. In the top right corner, a telemetry panel provides the following data:

|       |         |         |        |        |       |         |         |
|-------|---------|---------|--------|--------|-------|---------|---------|
| Wind  | 5 MPH   | Gusting | -1 MPH | Temp ° | 66 F  | Current | Weather |
| Speed | 2.2 MPH | AGL     | -23 ft | GPS-Ac | 16 ft | Battery | 50 %    |

Below the telemetry panel, there is a video player showing a live stream from the drone. The video title is 'YouTube Live Streaming from DJI Phantom 3 A...' and the progress bar shows 1:05 / 4:39. The video player includes standard controls like play, volume, and settings. At the bottom of the map, there is a Google logo and a footer with map data information: 'Map data ©2016 Google Imagery ©2016, DigitalGlobe, U.S. Geological Survey Terms of Use Report a map error'.

## Pilot View

Let's look at a video of the Pilots iPad during a flight.

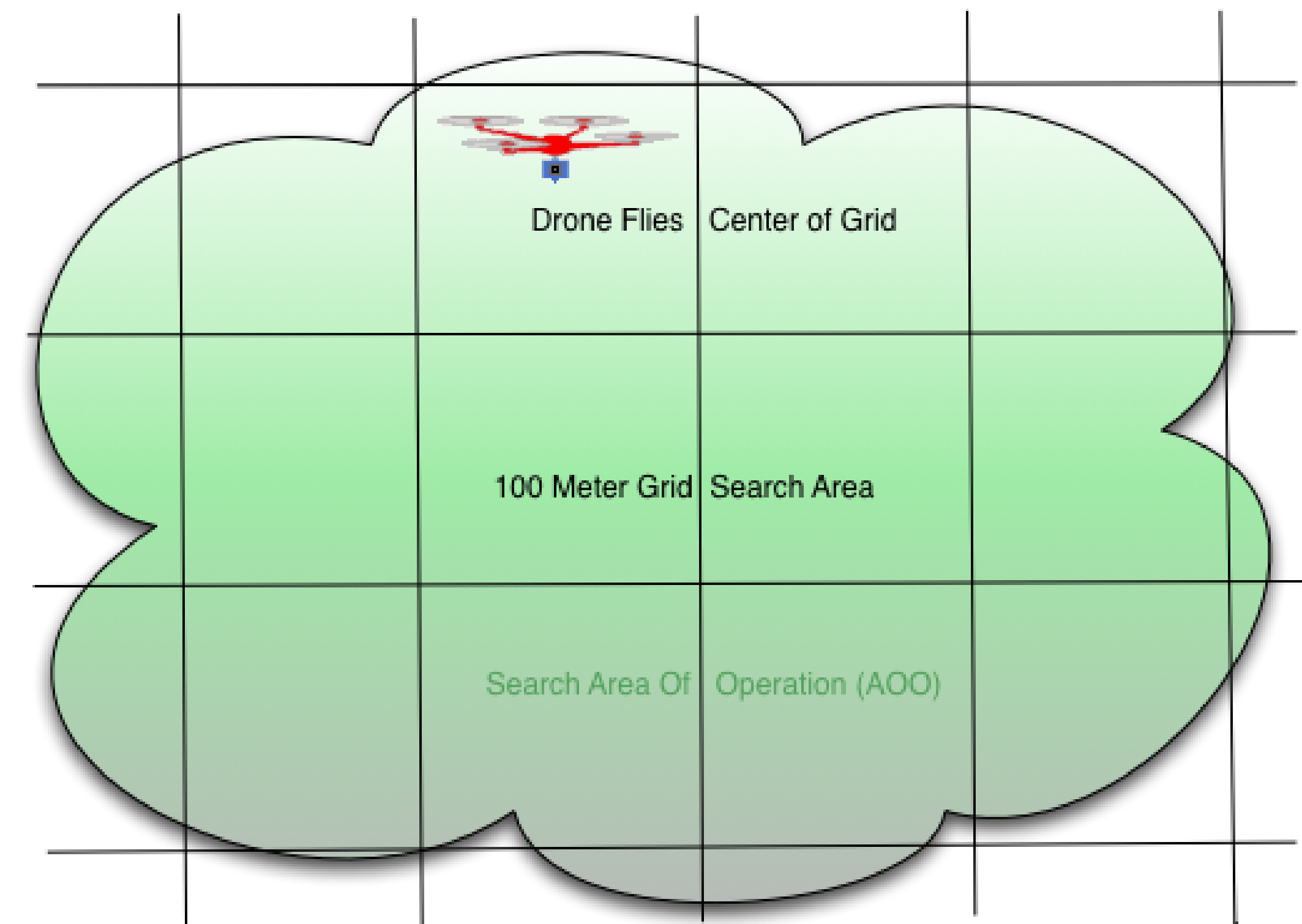
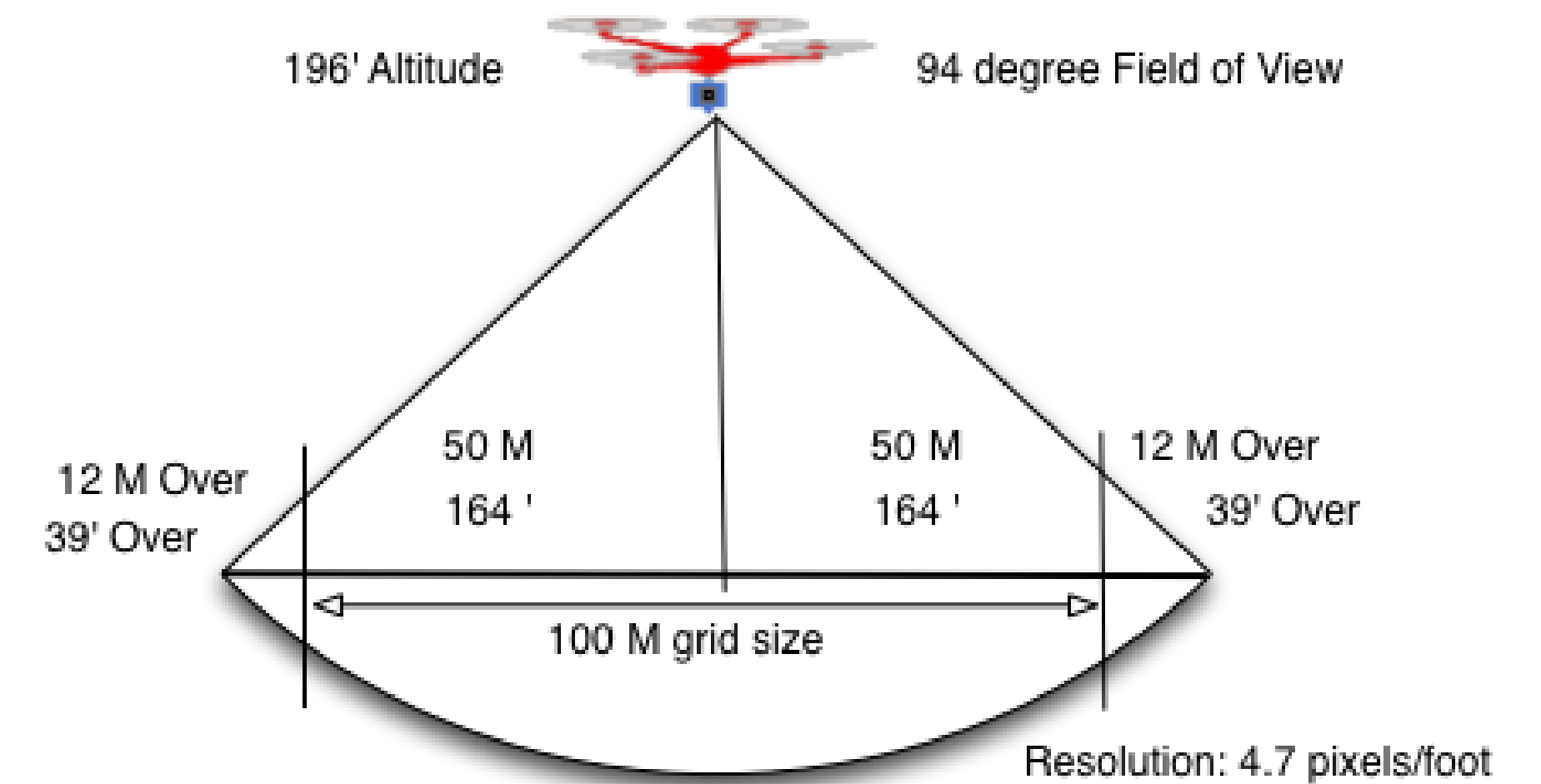
Note that the video quality of the iPad screen capture is poor. The screenshot you saw shows the actual quality the pilot sees.

For 100 meter search grids, an altitude of 196' with a camera gimbal angle of around  $45^\circ$  will show the full grid at about the centerline of the video.

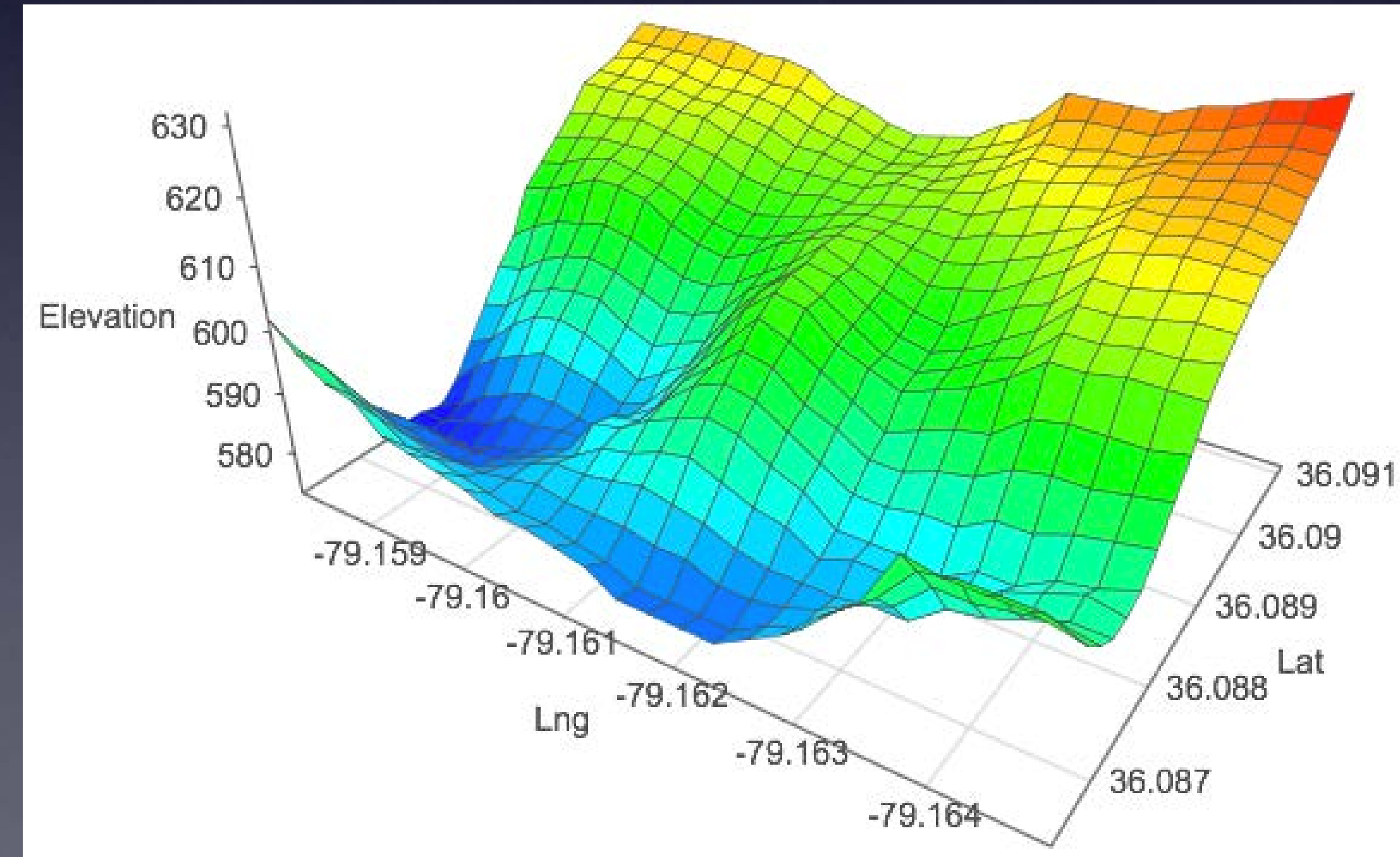
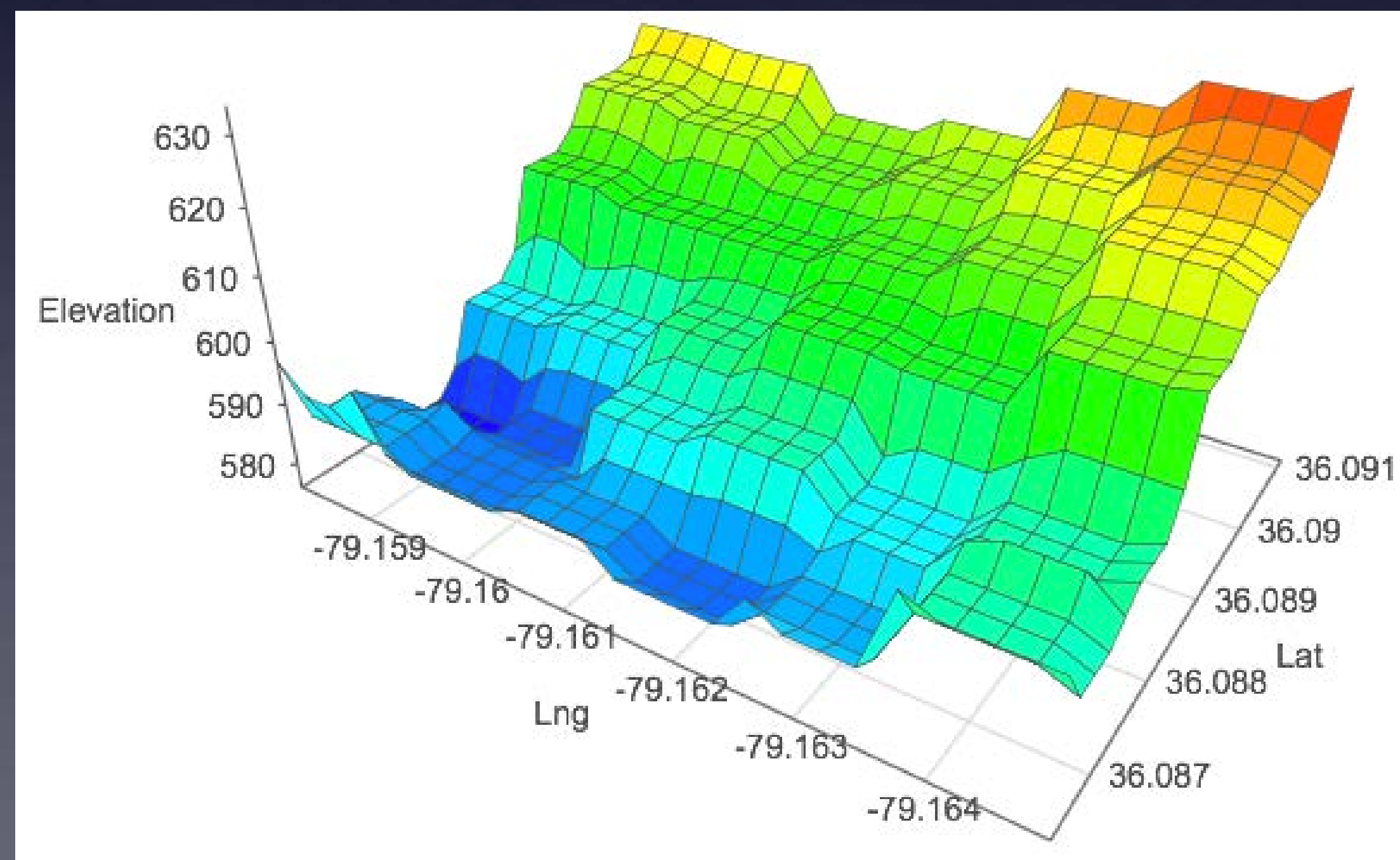
The resolution of the video is about 4.7 pixels per foot.

For a Thermal Imaging Camera (TIC) the resolution is about 1.5 pixels per foot (620H resolution). Lets hope that someday a TIC camera with HD resolution of 1280H becomes available. It won't be cheap...

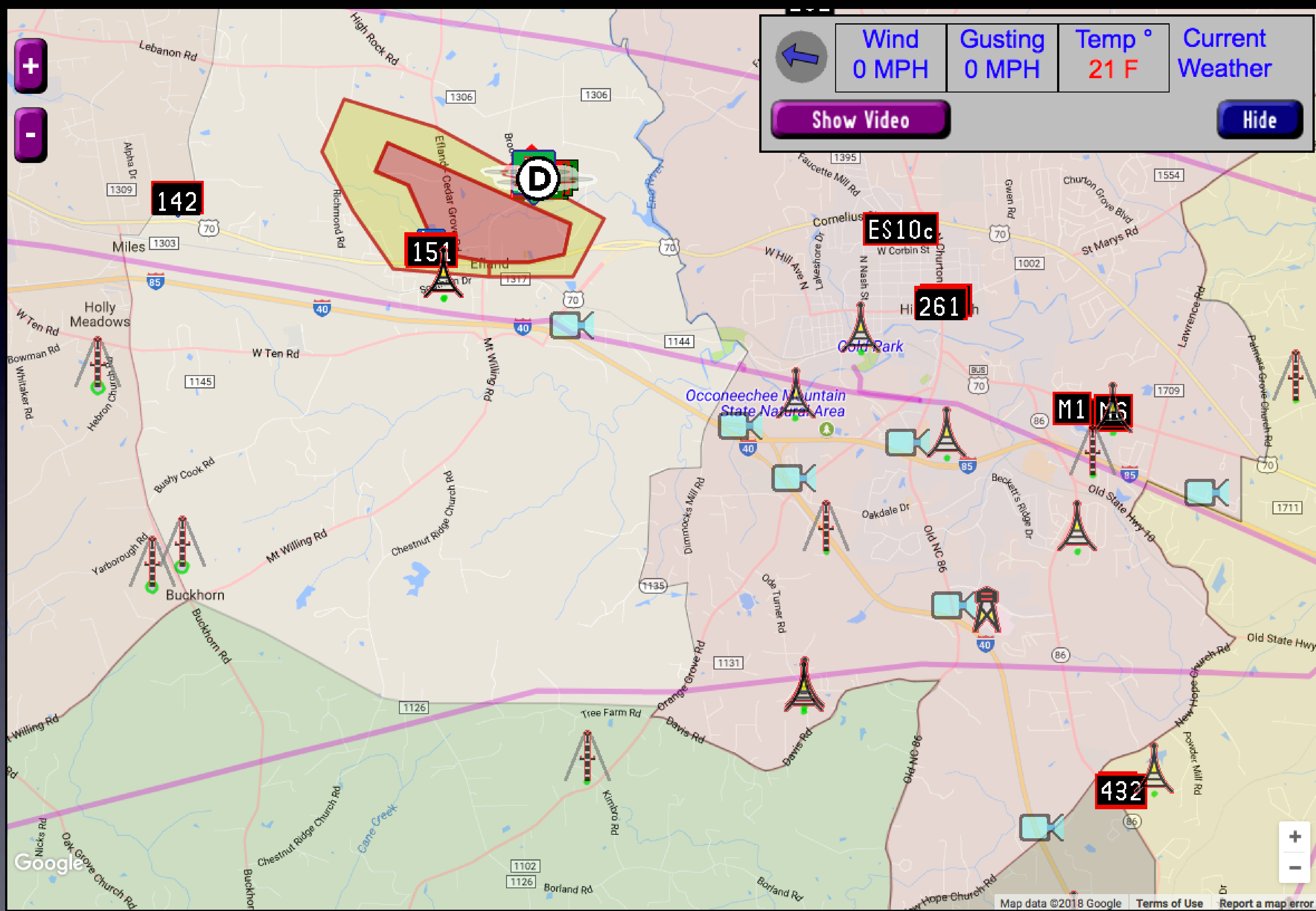
Drone Search Per-Pass Coverage Area



The server creates a 3-D elevation model of the terrain in the vicinity of the drone. It then smooths that terrain model. A button on the iPad can put the drone in a mode where it flies at a constant altitude above ground (AGL). This lets the pilot focus on flying and looking at the video even when in changing terrain.



You can enter obstructions like towers, water towers, tall buildings, power lines and small airport landing approach patterns.

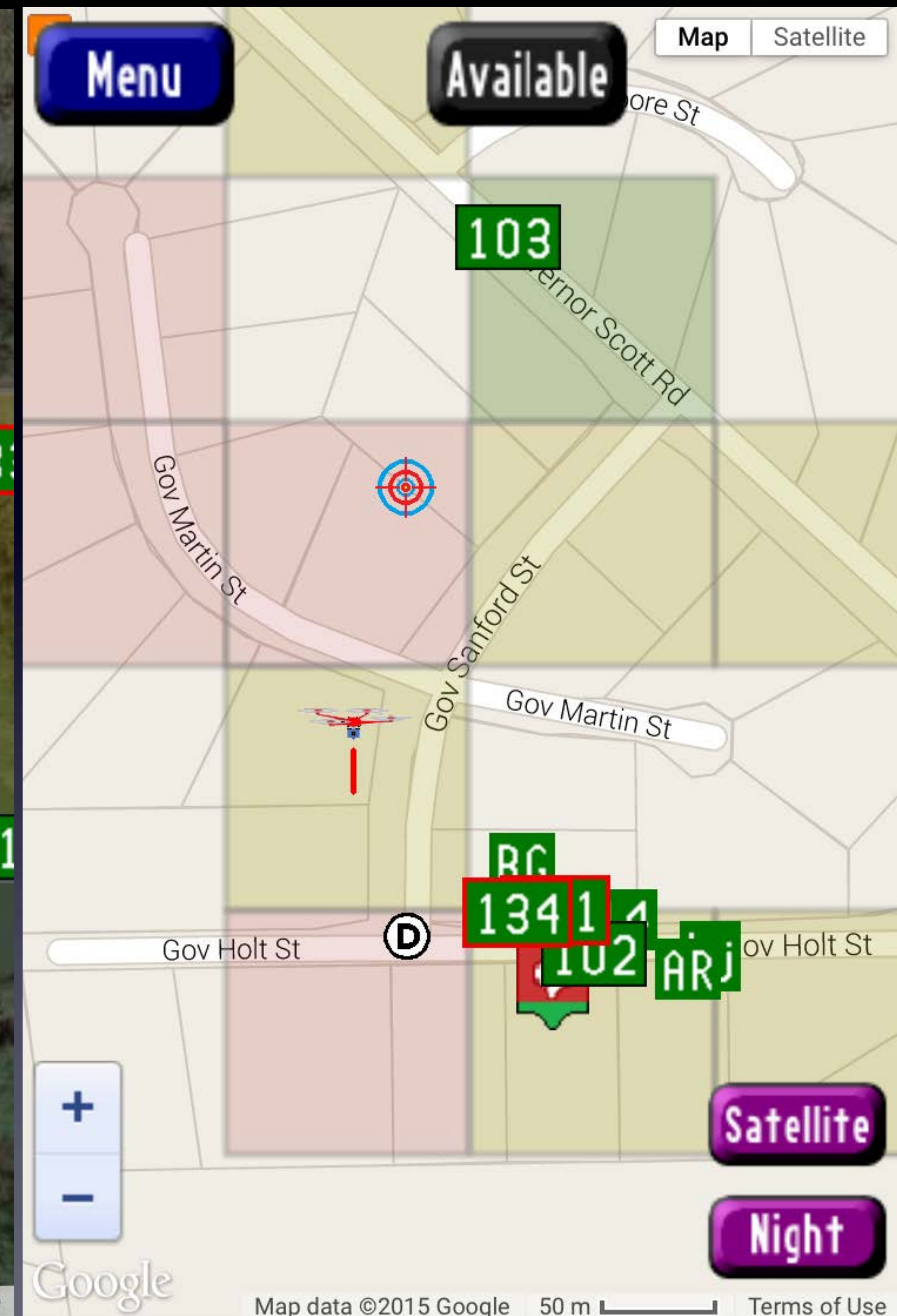
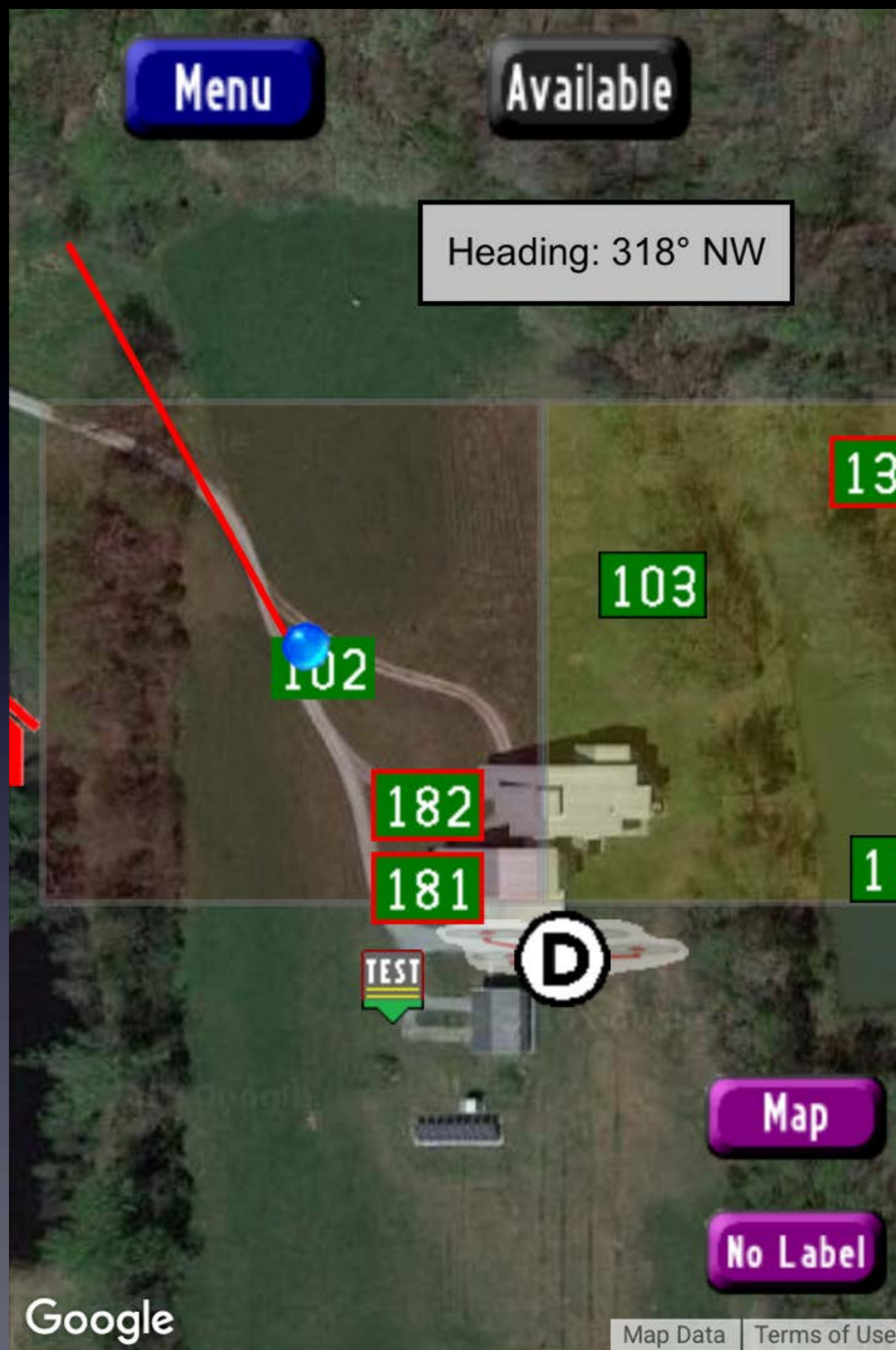


# Incident Command View

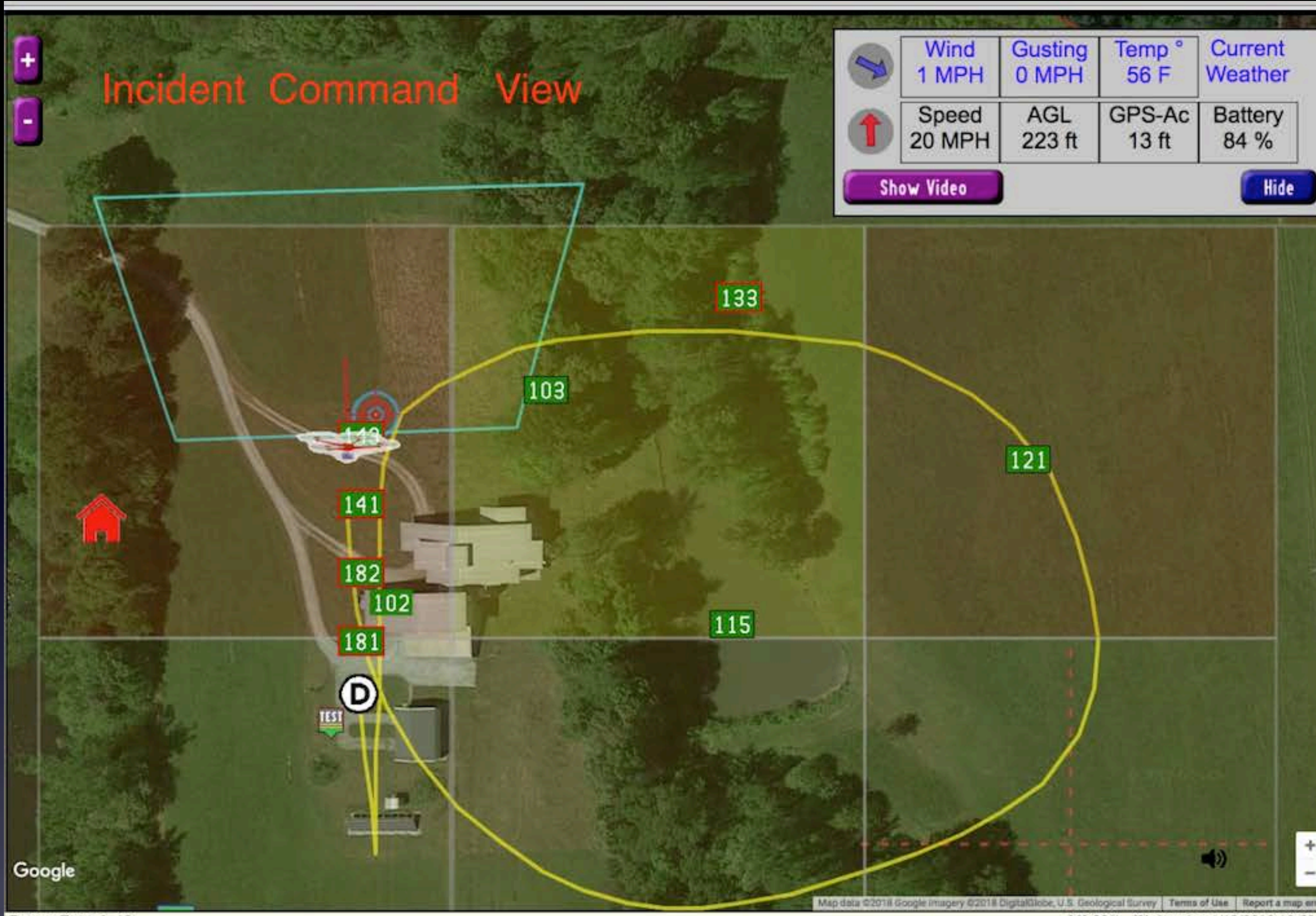
Video of the PageTrack “ÜberWatcher”  
screen. Shows “everything”.

# Responders:

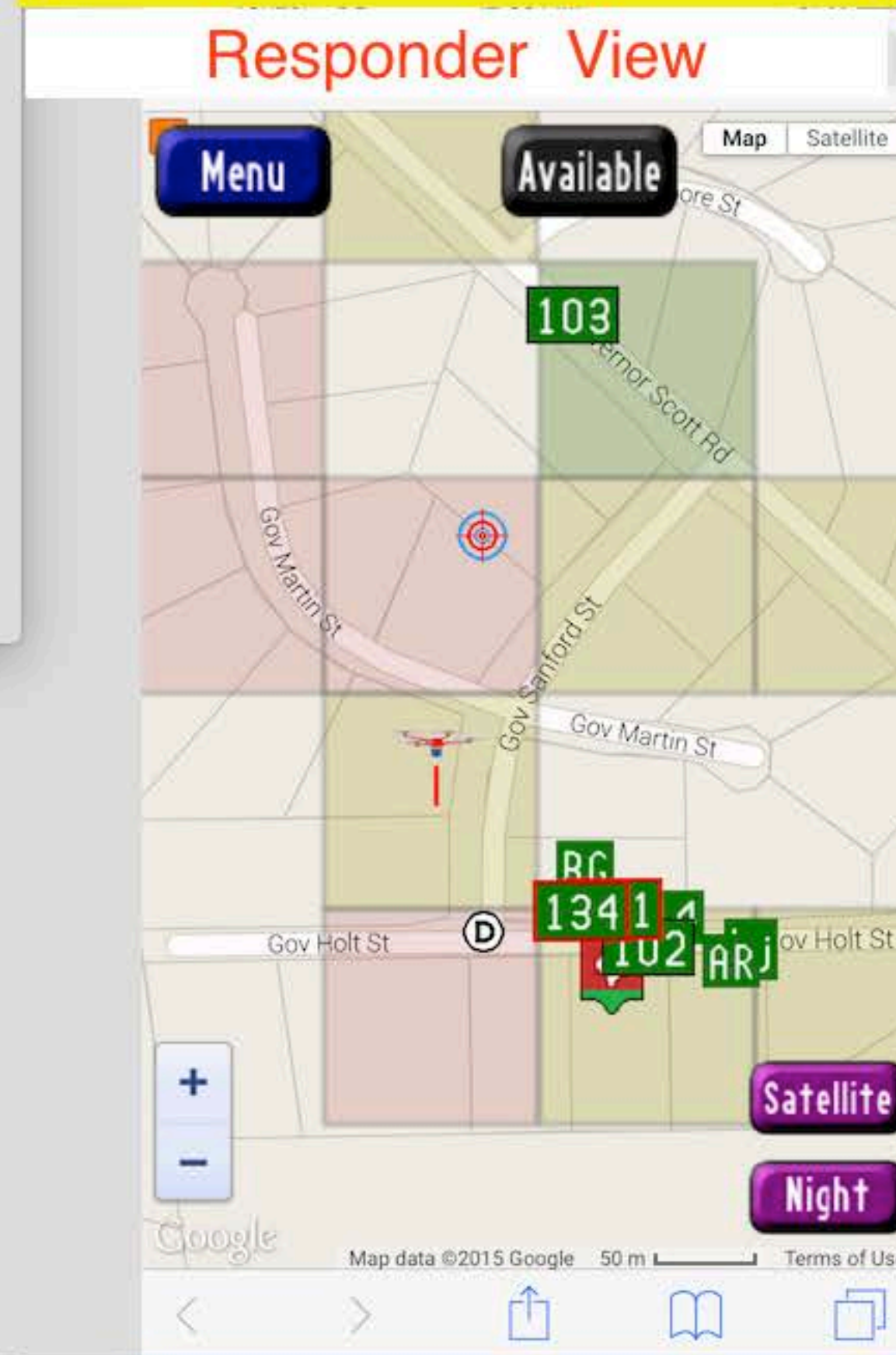
On the phone, they see other responders locations, dynamic search grids, drone location/heading, their heading, “Dropped Targets”, DronePort.







Responders can see the satellite or map view with locations of other responders, the drone, dropped targets and quality of search visible.



Incident Command can see where responders are, where the drone is, what area the pilot sees in the drone control video display, the path taken by the drone, any dropped targets the pilot placed.

The drone pilot sees the location of responders, search grid boundaries, grid center-lines, hazards and flight telemetry.

# Automatic Flight Log

No on like paperwork, so the system logs every flight. You can add notes about the equipment used, and the nature of the flight.

**Menu** **Drone Log Page** **DONE**

---

Drone: [drone-evfd](#) Sortie: **102** Pilot: Pete Hallenbeck Dur: 9 m Wed 8:44 1/10/18  
801 Brookhollow Rd (36.0889, -79.1617 ) Efland, NC

Drone: [drone-evfd](#) Sortie: **103** Pilot: Pete Hallenbeck Dur: 11 m Wed 9:01 1/10/18  
801 Brookhollow Rd (36.0889, -79.1617 ) Efland, NC

Menu

# Drone Log Page

DONE

Drone: [drone-evfd](#)

When: Wed 9:01 1/10/18

Sortie: [103](#) Pilot:

Duration: 11 min CFS: 05012018-99 Department: EVFD

Weather: 30° 29% Wind: 275° Speed: 3 Gust: 6 MPH

801 Brookhollow Rd, Efland, NC

Drone Pad/Launch Location: Lat: 36.0889 Long: -79.1617

Lens/Camera Info:

Battery ID(s):

Notes: [\(Enter ` for current time\)](#)

Notes for this flight

Show Drone Path

Advanced Path Search

Key information about the flight is logged.

The Pilot can add equipment information and general notes about the flight. Note the CFS number that can tie the flight back to the incident.

Buttons at the bottom display the flight path.

When you tap  
**Show Drone Path**  
you see the path  
of the flight the  
drone took during  
that sortie.

**Menu** **Drone Log Page** **DONE**

Map Satellite

Brookhollow Rd

Olivia Pope Way

low Rd

McGowan Creek

McGowan Creek

McGowan Creek

McGowan Creek

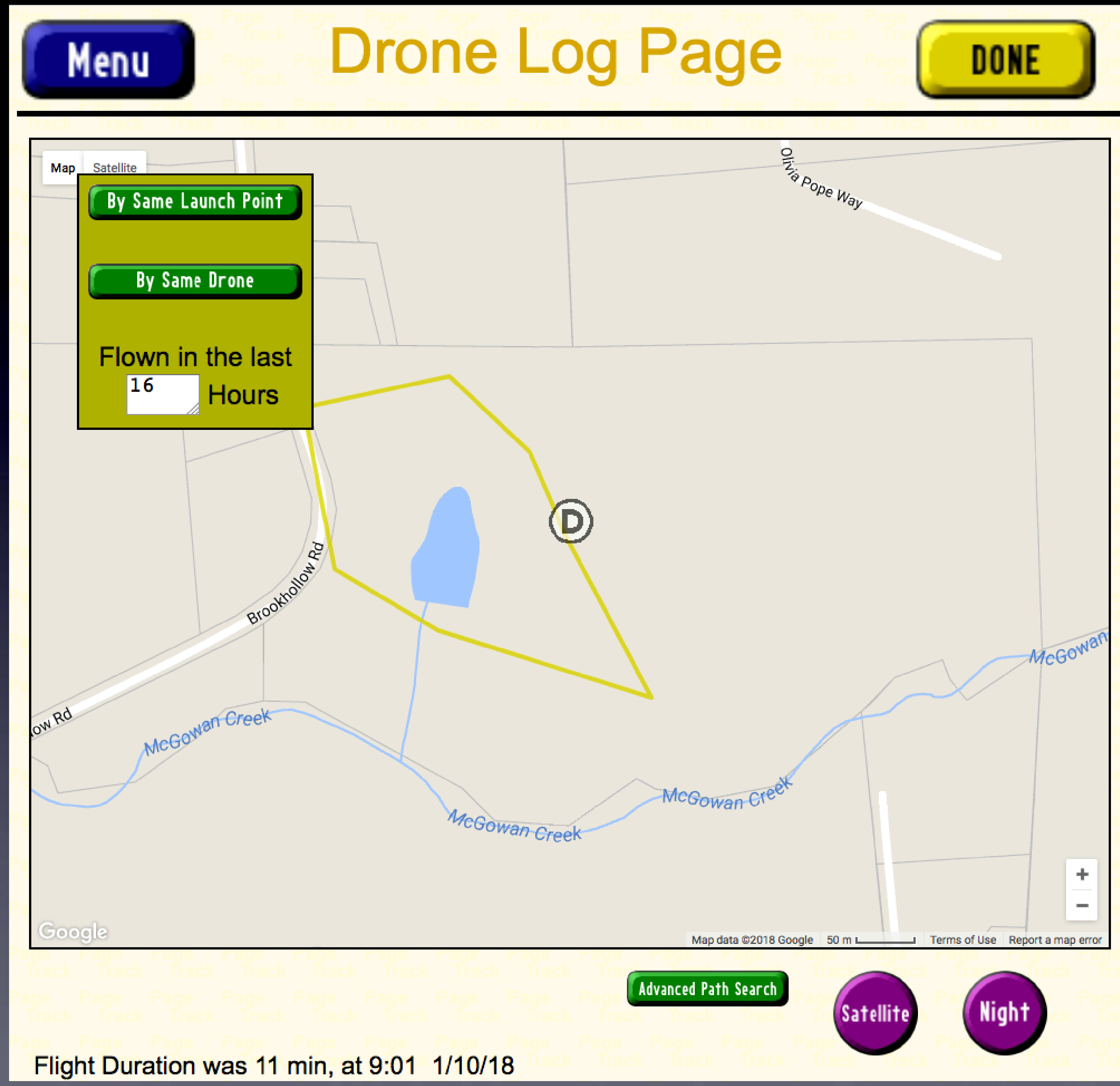
Google

Map data ©2018 Google 50 m Terms of Use Report a map error

**Advanced Path Search** **Satellite** **Night**

Flight Duration was 11 min, at 9:01 1/10/18

When you tap  
**Advanced Path Search**  
you can display  
multiple sorties at  
either the same  
launch point or all  
the sorties taken by  
a given drone.



Now you can see all the paths taken by the drone for a given launch point / incident.

Menu Drone Log Page DONE

Map Satellite

Brookhollow Rd

Olivia Pope Way

low Rd

McGowan Creek

McGowan Creek

McGowan Creek

McGowan

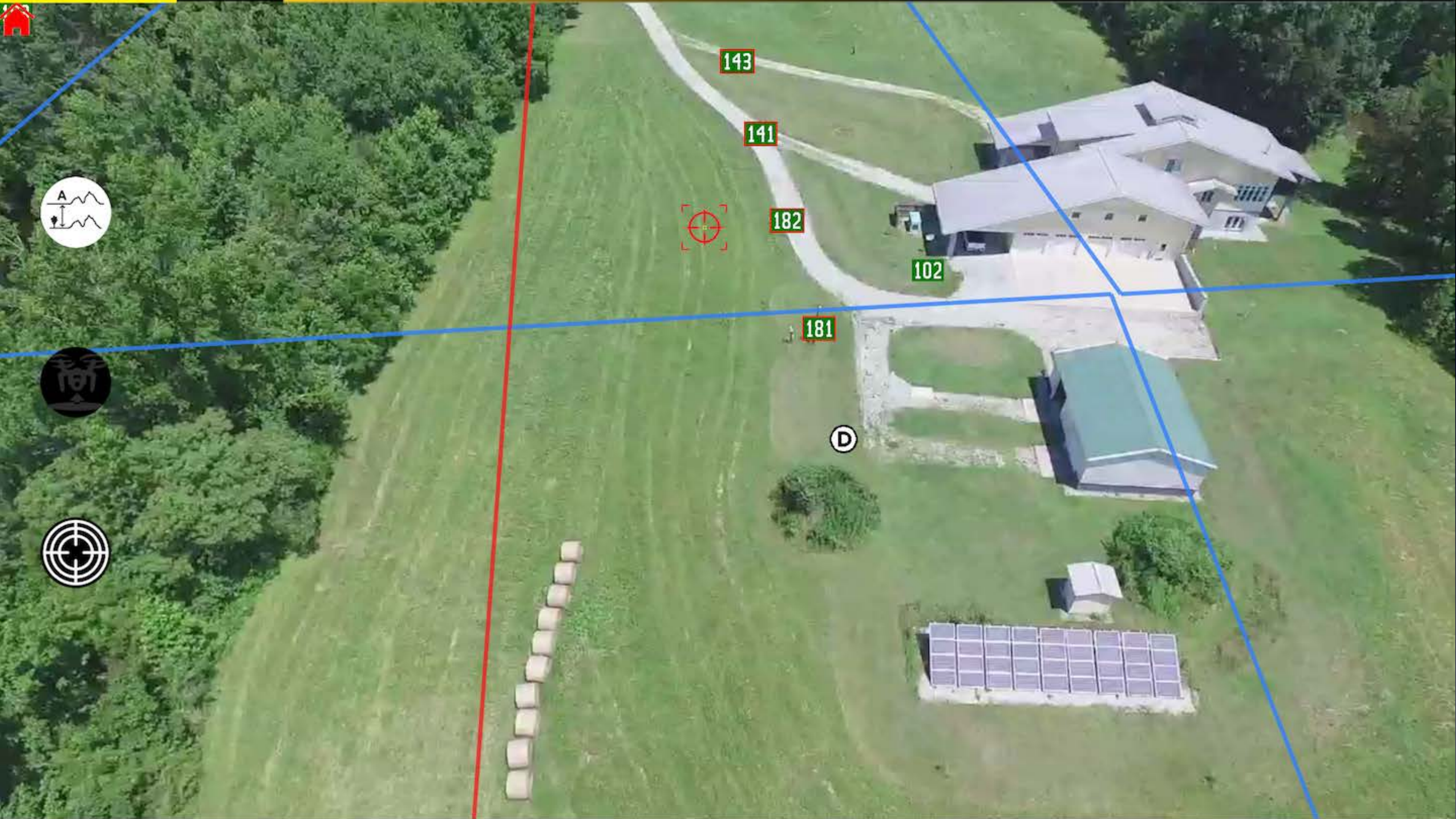
Google

Map data ©2018 Google 50 m Terms of Use Report a map error

Advanced Path Search

Satellite Night

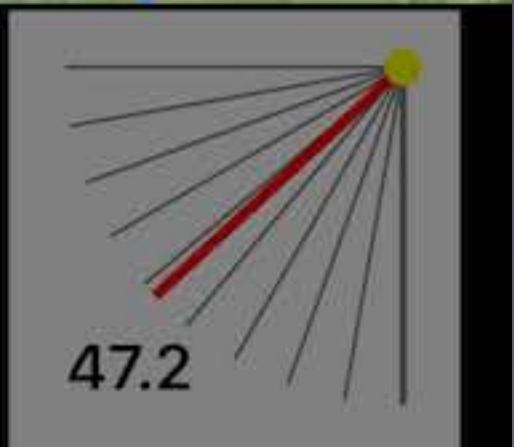
Showing 2 flight paths



Thank You  
for your  
attention.

Any  
Questions?

|  |                |                  |                 |                     |                      |
|--|----------------|------------------|-----------------|---------------------|----------------------|
|  | Wind<br>3 MPH  | Gusting<br>5 MPH | Temp °<br>87 F  | Vertical<br>0.0 MPH | DIST.<br>194 ft      |
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*MEASURE FROM IMAGES*

Presented by Tyler Holloway  
GSC Surveying, Inc. & Go Unmanned,  
Inc.



# What is Pix4D?

- Photo Processing
- Georeferenced data
- High accuracy point cloud



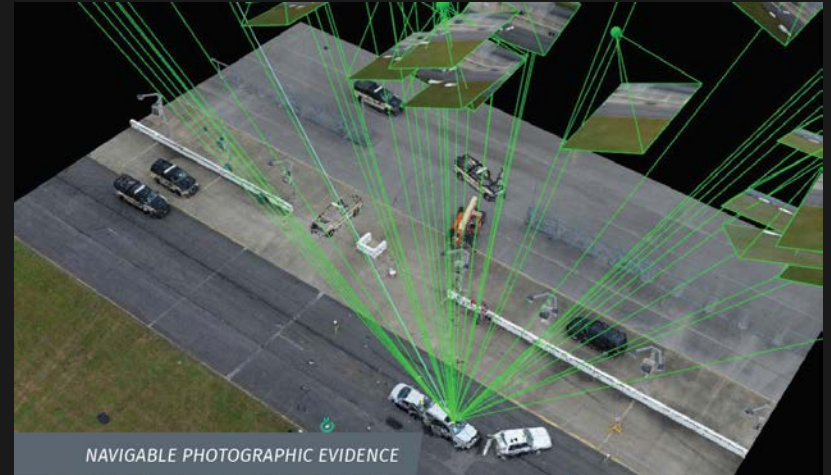
# Pix4D in Forensics

- Fly or take photos around the accident scene
- Process using Pix4D
- Full model to scale of the scene



# Crime and Accident Scene Reconstruction

- Reduced time on scene
- ¼ of the time it normally takes with traditional measures
- Fast road re-opening



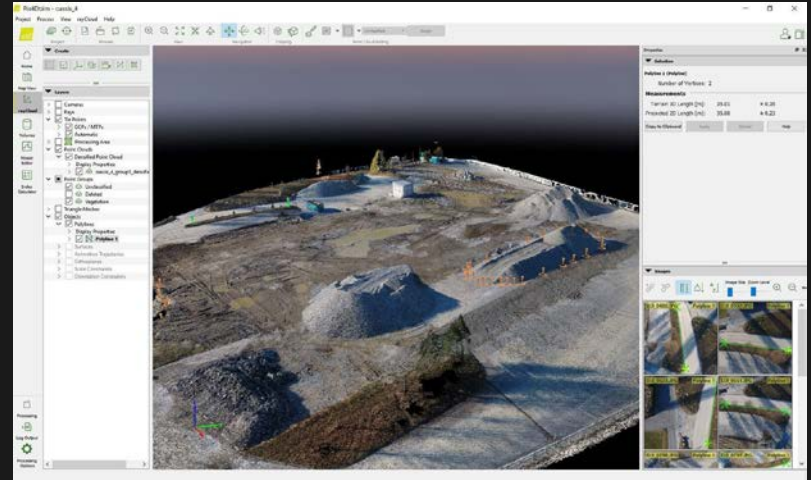
# Navigable photographic evidence

- Hundreds of photos rendered into a 3D model
- Investigations continue after the road reopens
- Long term photo and 3D evidence of the scene
- Compatible with investigation software



# Pix4D Cloud Processing

- Save projects on Pix4D servers
- Process quickly and save initial costs
- Easily reopen projects



# Pix4D User Workshop | Raleigh, NC

This is a technical workshop for professionals using drones in their practice. The workshop will introduce you to creating accurate reconstructions and improving your results using Pix4D mapping software. It is an in-person event taught by Pix4D staff.



[GoUnmanned.com/Pix4D-Workshop](https://GoUnmanned.com/Pix4D-Workshop)

# Questions?

Contact Go Unmanned to learn more about Pix4D.

866.UAV.5777 | [www.GoUnmanned.com](http://www.GoUnmanned.com)

